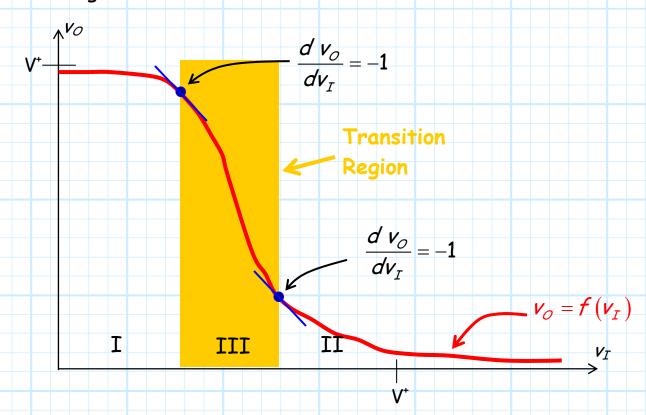
Noise Margins

The transfer function of a digital inverter will typically look something like this:



Note that there are essentially three regions to this curve:

- I. The region where v_I is relatively **low**, so that the output voltage v_O is **high**.
- II. The region where v_I is relatively **high**, so that the output voltage v_O is **low**.
- III. The transition region, where the input/output voltage is in an indeterminate state (i.e, an ambiguous region between high and low.

Note that the **transition region** is rather **arbitrarily** defined by the points on the transfer function where the magnitude of the **slope** is **greater than one** (i.e., where $|dv_O/dv_I| > 1.0$).

Although this transfer function looks rather simple, there are actually several parameters that we use to characterize this transfer function—and thus characterize the digital inverter as well!

1. First of all, let's consider the case when $v_I=0$. The output of the digital inverter in this condition is defined as V_{OH} (i.e., $OH \rightarrow$ "output high"), i.e.:

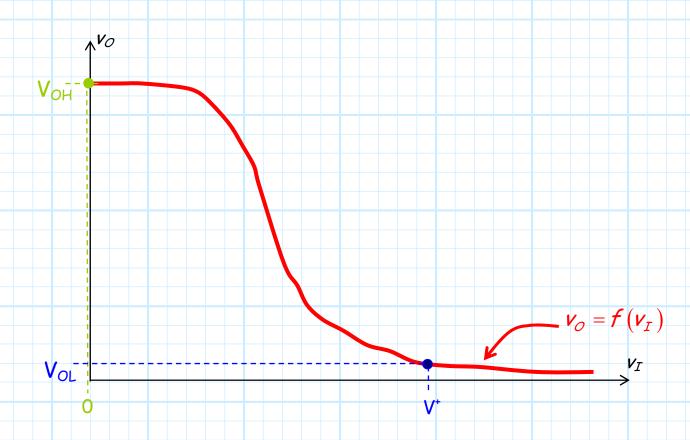
$$V_{OH} \doteq v_O$$
 when $v_I = 0$

Thus, V_{OH} is essentially the "ideal" inverter high output, as it is the output voltage when the inverter input is at its ideal low input value v_I =0. Typically, V_{OH} is a value just slightly less than supply voltage V^+ .

2. Now, let's consider the case when $v_I = V^+$. The output of the digital inverter in this condition is **defined** as V_{OL} (i.e., $OL \rightarrow$ "output low"), i.e.:

$$V_{OL} \doteq v_{\mathcal{O}}$$
 when $v_{\mathcal{I}} = V^{\dagger}$

Thus, V_{OL} is essentially the "ideal" inverter low output, as it is the output voltage when the inverter input is at its ideal high input value $v_I = V^{\dagger}$. Typically, V_{OL} is a value just slightly greater than 0.



3. The "boundary" between region I and the transition region of the transfer function is denoted as V_{IL} (i.e., $IL \rightarrow$ "input low"). Specifically, this is the value of the input voltage that corresponds to the first point on the transfer function where the slope is equal to -1.0 (i.e., where $dv_O/dv_I = -1.0$).

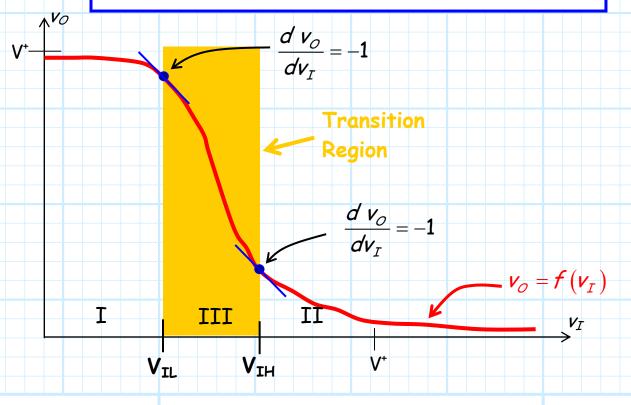
Effectively, the value V_{IL} places an **upper bound** on an acceptably "low" value of input ν_I —any ν_I greater than V_{IL} is **not** considered to be a "low" input value. I.E.:

 $v_{\scriptscriptstyle I}$ considered "low" only if $v_{\scriptscriptstyle I} < V_{\scriptscriptstyle IL}$

4. Likewise, the "boundary" between region II and the transition region of the transfer function is denoted as V_{IH} (i.e., IH \rightarrow "input high"). Specifically, this is the value of the input voltage that corresponds to the second point on the transfer function where the slope is equal to -1.0 (i.e., where $dv_o/dv_I = -1.0$).

Effectively, the value V_{IH} places a **lower bound** on an acceptably "**high**" value of input v_I —any v_I lower than V_{IH} is **not** considered to be a "high" input value. I.E.:

 v_I considered "high" only if $v_I > V_{IH}$



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Note then that the input voltages of the transition region (i.e., $V_{IL} < v_I < V_{IH}$) are ambiguous values—we cannot classify them as either a digital "low" value or a digital "high" value.

Accordingly, the **output** voltages in the transition region are both significantly less that V_{OH} and significantly larger then V_{OL} . Thus, the **output** voltages that occur in the transition region are **likewise ambiguous** (cannot be assigned a logical state).

Lesson learned -> Stay away from the transition region!

In other words, we must ensure that an **input** voltage representing a logical "**low**" value is **significantly lower** than $V_{\rm IL}$, and an **input** voltage representing a logical "**high**" value is **significantly higher** than $V_{\rm IH}$.

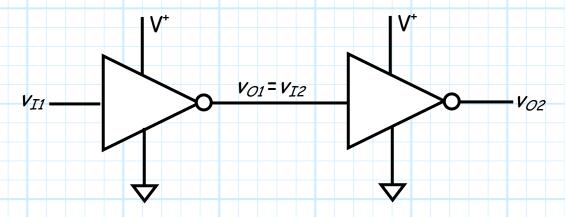


Q: Seems simple enough! Why don't we end this exceedingly dull handout and move on to something more interesting!?

A: Actually, staying out of the transition region is sometimes more difficult than you might first imagine!

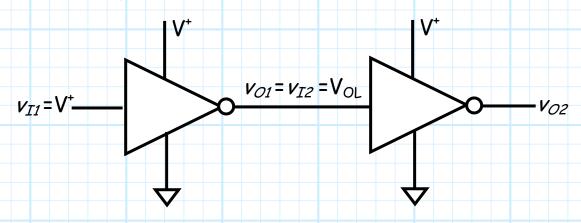
The reason for this is that in a digital system, the devices are connected together—the input of one device is the output of the other, and vice versa.

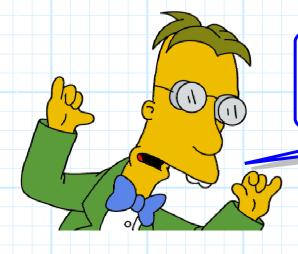
For example:



Say that the **input** to the **first** digital inverter is $v_{I1} = V^+$. The **output** of that inverter is therefore $v_{O1} = V_{OL}$. Thus, the **input** to the **second** inverter is **likewise** equal to V_{OL} (i.e.,

$$v_{I2} = v_{O2} = V_{OL}$$
).





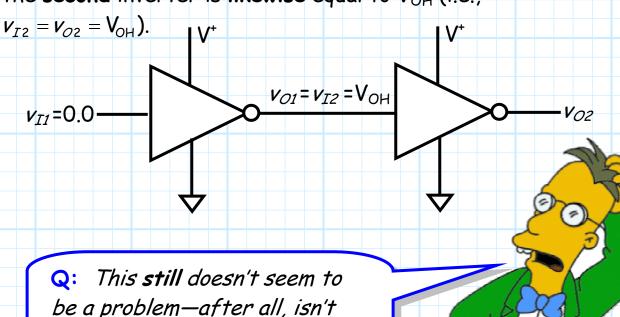
Q: So? This doesn't seem to be a problem—after all, isn't V_{OL} much lower than V_{IL} ??

A: True enough! The input $v_{I2}=V_{OL}$ is typically well below the maximum acceptable value V_{IL} . In fact, we have a specific name for the difference between V_{IL} and V_{OL} —we call this value Noise Margin (NM):

$$NM_L = V_{TL} - V_{OL}$$
 $[Vo/ts]$

The noise margin essentially tells us **how close** we are to the **ambiguous** transition region for a typical case where $v_I = V_{OL}$. Of course, we do **not** wish to be close to this transition region at all, so **ideally** this noise margin is **very large**!

Now, consider the alternate case where v_{II} =0.0 V. The output of the first inverter is therefore $v_{O1} = V_{OH}$. Thus, the input to the second inverter is likewise equal to V_{OH} (i.e.,



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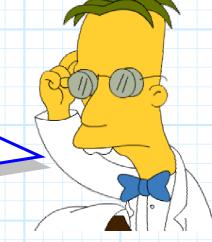
 V_{OH} much larger than V_{IH} ??

A: Again, this is **true** enough! The input $v_{I2}=V_{OH}$ is typically well above the minimum acceptable value V_{IH} . We can again specify the difference between V_{IH} and V_{OH} as a noise margin (NM):

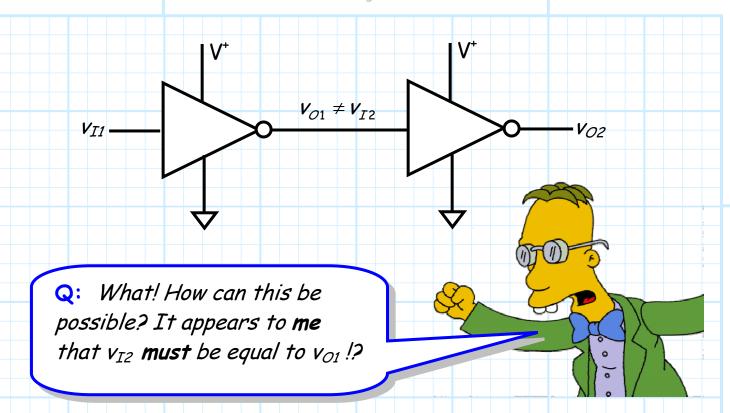
$$NM_{H} = V_{OH} - V_{IH}$$
 $\lceil Vo/ts \rceil$

This noise margin essentially tells us how close we are to the ambiguous transition region for a typical case where $v_I = 0.0 \text{ V}$. Of course, we do not wish to be close to this transition region at all, so ideally this noise margin is very large!

Q: I don't see why we care about the values of these "noise margins". Isn't the simple fact that $V_{OL} < V_{IL}$ and $V_{OH} > V_{IH}$ sufficient?



A: Ideally yes. However, in our example we have made one important assumption that in fact may not be true! It turns out that in a real digital circuit, v_{I2} may not be equal to v_{O1} !!



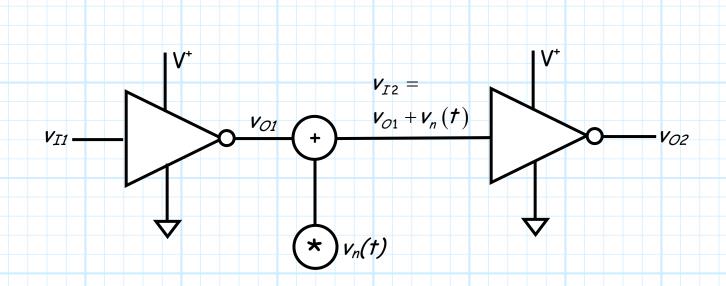
A: It turns out that for a real digital circuit, a lot can happen between the output of one device and the input to another.

The voltage at the input of a device might be affected by many sources—only one of which is the output device connected to it!

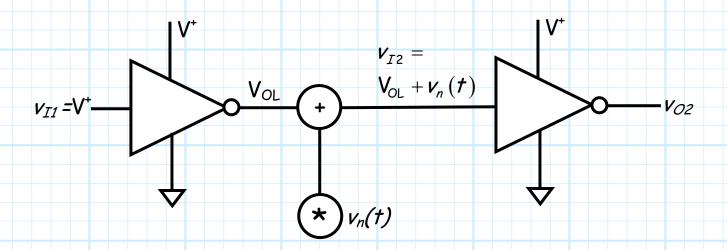
Examples of these "extra" sources include:

- 1. Thermal noise
- 2. Coupled signals
- 3. Power supply transients

We will **combine** the effect of **all** of these sources together into one "**noise**" source $\nu_n(t)$. Thus, a **better model** for our digital circuit example is:



Now, let's **reconsider** the case where $v_{II} = V^{\dagger}$. We find that the **input** to the **second** digital inverter is then $v_{I2} = V_{OL} + v_n(t)$:



Now we see the **problem!** If the **noise** voltage is **too large**, then the **input** to the second inverter will **exceed** the maximum low input level of $V_{\rm IL}$ —we will have entered the dreaded **transition region!!!!**

To avoid the transition region, we find that the input to the second inverter must be less than $V_{\rm IL}$:

$$V_{OL} + V_n(t) < V_{IL}$$

$$V_n(t) < V_{IL} - V_{OL}$$

$$V_n(t) < NM_L$$

Look at what this means! It says to avoid the transition region (i.e., for the input voltage to have an unambiguously "low" digital level), the noise must be less than noise margin NM_L for all time t!

Thus, if the **noise margin** NM_L is **large**, the noise $v_n(t)$ can be large **without** causing any deleterious effect (deleterious effect) transition region). Conversely, if the noise margin NM_L is **small**, then the noise **must** be small to avoid **ambiguous** voltage levels.

Lesson learned -> Large noise margins are very desirable!

Considering again the example circuit, only this time with v_I =0.0 V, we find that to avoid the transition region (verify this for yourself!):

$$V_{OH} + V_n(t) > V_{IH}$$

$$V_n(t) > V_{IH} - V_{OH}$$

$$V_n(t) > -NM_H$$

$$-V_n(t) < NM_H$$

Note that the noise $v_n(t)$ is as likely to be positive as negative—it is in fact negative valued noise that will send v_{I2} to a value less than V_{IH} !

Thus, we can make the statement that the **magnitude** of the **noise** $v_n(t)$ must be **less** than the **noise margins** to avoid the ambiguous values of the disturbing **transition region**! I.E., make sure that:

$$|v_n(t)| < NM$$
 for all time t